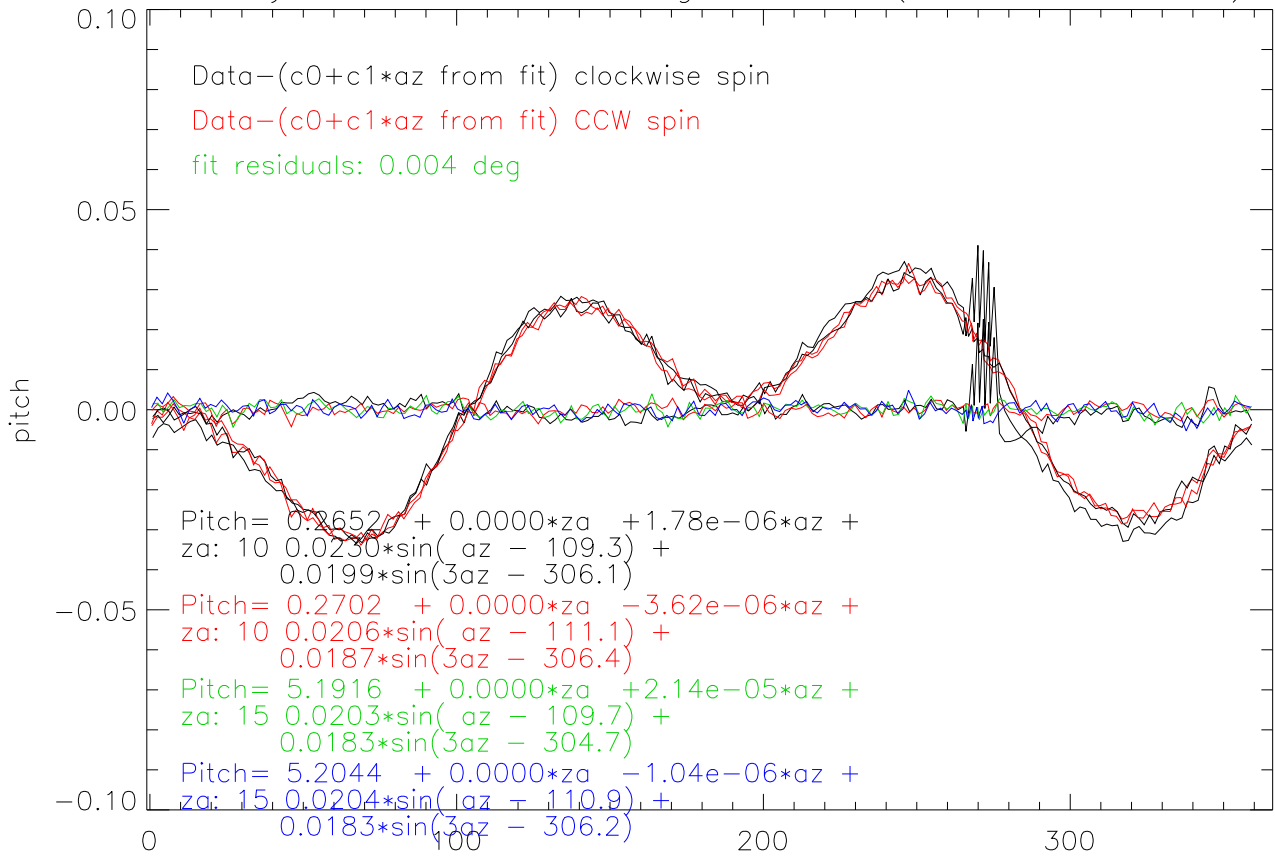


10may11 tilt sensor az swings PITCH - (c0+c1*az from fit)



10may11 tilt sensor az swings Roll - (c0+c1*az from fit)

